

SXYx 2 axes / ZS

● XY type ● Cable carrier

Ordering method

SXYx - C				15		RCX222				
Model	Cable	Combination	X-axis stroke	ZR-axis	Z-axis stroke	Cable length	Controller	Usable for CE	Input/Output selection 1	Input/Output selection 2
	F1 F3		15 to 105cm	ZS12 ZS6		3L: 3.5m (Standard) 5L: 5m 10L: 10m	RCX222 DRCX0505	No entry: Standard E: CE marking	N: NPN P: PNP CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link	No entry: None Nt: OP.DIO24/16 (NPN) Pt: OP.DIO24/17 (PNP) EN: Ethernet

Note 1. NPN and Ethernet cannot be selected if using CE marking.
 Note 2. Available only for the master.
 Note 3. Only when CC or DN or PB was selected for I/O select 1 above. EN can be selected in I/O select 2.

Specification

	X-axis	Z-axis ZS12	Z-axis ZS6
Axis construction <small>Note 1</small>	F14	-	
AC servo motor output (W)	100	60	
Repeatability <small>Note 2</small> (mm)	+/-0.01	+/-0.02	
Drive system	Ball screw (Class C7)	Ball screw (Class C10)	
Ball screw lead (Deceleration ratio) (mm)	20	12	6
Maximum speed <small>Note 3</small> (mm/sec)	During RCX240 use	1200	500
	During DRCX use	1200	450
Moving range (mm)	150 to 1050	150	
Robot cable length (m)	Standard: 3.5 Option: 5,10		

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots.
 Note 2. Positioning repeatability in one direction.
 Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

Maximum payload (kg)

Y stroke (mm)	ZS12	ZS6
150 to 1050	3	5

Controller

Controller	Operation method
RCX222	Programming / I/O point trace / Remote command / Operation using RS-232C communication
DRCX0505	

SXYx 2 axes / ZS (F1)

Detail of section A
 φ5
 41
 36
 φ12⁰_{-0.018}
 M8 x 1.25
 Depth15

Detail of section B
 (18.5)
 5.5
 φ10H7
 9

Cross-section of cable carrier
 73
 57
 φ9.7
 φ8.2
 φ7.6

Notes:
 Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
 Note 2. The shaded position indicates an user cable extraction port.
 Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

X stroke	150	250	350	450	550	650	750	850	950	1050
L	405	505	605	705	805	905	1005	1105	1205	1305
K	200	100	200	100	200	100	200	100	200	100
C	240	240	420	420	600	600	780	780	960	960
M	0	1	1	2	2	3	3	4	4	5
N	4	6	6	8	8	10	10	12	12	14

Z stroke	150
Maximum speed for each stroke (mm/sec) <small>Note 3</small>	
X-axis	1200
Speed setting	-
	960
	780
	600
	540
	80%
	65%
	50%
	45%

APPLICATION
 TRANSERO
 FLIP-X
 PHASER
 XY-X
 YK-XG
 YP-X
 CLEAN
 CONTROLLER
 INFORMATION
 Arm type
 Gantry type
 Moving arm type
 Pole type
 XZ type