

Arm type

Whipover

Z-axis: clamped base / moving table type (100W)+R-axis

## ■ Ordering method

SXYx - S			ZRF		RCX240		BB					
Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable length	Controller	Usable for	Option I/O Notes	Network option	Battery
A1			15 to 85cm	15 to 65cm		15 to 35cm	3L: 3.5m (Standard) 5L: 5m 10L: 10m		No entry: Standard E: CE marking	N.P: Standard I/O 16/8 N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link	BB: 4 pcs
A2												
A3												
A4												

Note 1. N to N4 if NPN was selected, or P to P4 if PNP was selected for the I/O board.

Note 2. Available only for the master.

## ■ Specification

	X-axis	Y-axis	Z-axis	R-axis
Axis construction Note 1	F14H	F14	F10-BK	R5
AC servo motor output (W)	200	100	100	50
Repeatability Note 2 (XYZ mm) (R °)	+/-0.01	+/-0.01	+/-0.01	+/-0.0083
Drive system	Ball screw (Class C7)	Ball screw (Class C7)	Ball screw (Class C7)	Harmonic gear
Ball screw lead (Deceleration ratio) (mm)	20	20	10	(1/50)
Maximum speed Note 3 (XYZ: mm/sec) (R: °/sec)	1200	1200	600	360
Moving range (XYZ mm) (R °)	150 to 850	150 to 650	150 to 350	360
Robot cable length (m)		Standard: 3.5 Option: 5,10		

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

## ■ Maximum payload (kg)

Y stroke (mm)	Z stroke (mm)		
	150	250	350
150	6	6	6
250	6	5	4
350	4	3	2
450	3	2	1
550	2	1	-
650	1	-	-

## ■ Controller

Controller	Operation method
RCX240	Programming / I/O point trace / Remote command / Operation using RS-232C communication

## SXYx 4 axes / ZRF A1

