■ Ordering method

YK220XC-100

Arm length 220mm Maximum payload 1kg

Z axis stroke - Cable length

RCX340-4

Specify various controller setting items. RCX340 ▶ P.542 RCX240S

- CE Marking - Expansion I/O - Network option - iVY System - Gripper - Battery Specify various controller setting items. RCX240/RCX240S ▶ P.532

| ■ Basic specifications | | | | | |
|------------------------------------------------------|--------------------|---------------------------------------------------|--------|---------|----------|
| | | X axis | Y axis | Z axis | R axis |
| Axis specifications | Arm length (mm) | 111 | 109 | 100 | - |
| | Rotation angle (°) | +/-120 | +/-140 | - | +/-360 |
| AC servo motor output (W) | | 50 | 30 | 30 | 30 |
| Repeatability Note 1 (XYZ: mm) (R: °) | | +/-0.01 | | +/-0.01 | +/-0.004 |
| Maximum speed (XYZ: m/sec) (R: °/sec) | | 3.4 | | 0.7 | 1700 |
| Maximum payload (kg) | | 1.0 | | | |
| Standard cycle time: with 0.1kg payload Note 2 (sec) | | 0.45 | | | |
| R-axis tolerable moment of inertia Note 3 (kgm²) | | 0.01 | | | |
| User wiring (sq × wires) | | 0.1 × 8 | | | |
| User tubing (Outer diameter) | | ф3 × 2 | | | |
| Travel limit | | 1.Soft limit, 2.Mechanical stopper (X, Y, Z axes) | | | |
| Robot cable length (m) | | Standard: 3.5 Option: 5, 10 | | | |
| Weight (kg) (Excluding robot cable) Note 4 | | 6.5 | | | |
| Robot cable weight | | 1.5kg (3.5m) 2.1kg (5m) 4.2kg (10m) | | | |
| Degree of cleanliness | | CLASS 10 (0.1 µm base) | | | |

Controller | Power capacity (VA) | Operation method Programming / I/O point trace / Remote command / RCX340 500 RCX240S Operation using RS-232C communication

Intake air (Ne/min)

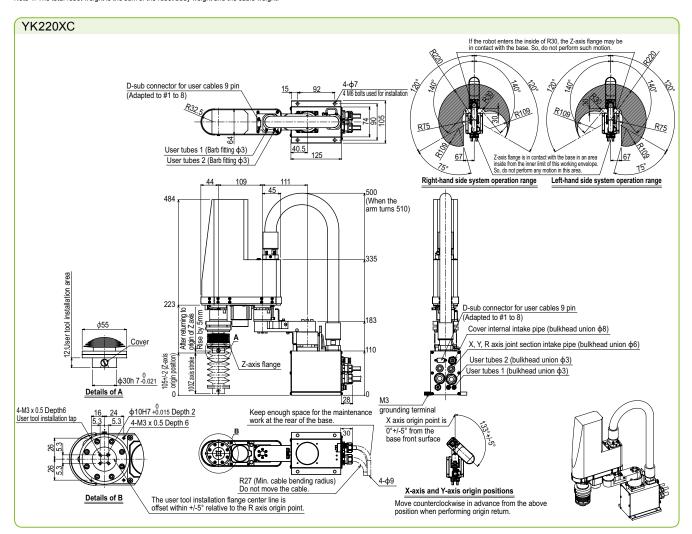
Note 1. This is the value at a constant ambient temperature.

Note 2. When reciprocating 100mm in horizontal and 25mm in vertical directions.

Note 3. There are limits to acceleration coefficient settings.

Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

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Controller

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